PSS 31 - Shaft 14 mm solid



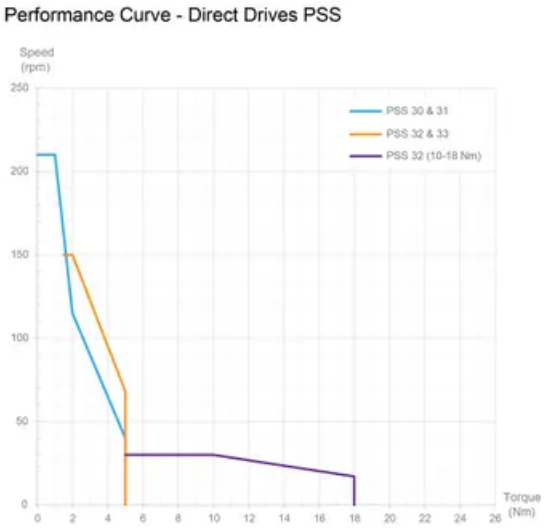
• Positioning system with IP 65
• Absolute measuring system, without battery
• Galvanically separated supply voltages between control and motor and bus
• Absolute encoder eliminates the need for reference runs during system setup and installation of replacements
• Easy address assignment directly on the device using integrated address switches (not for IO-Link)
• Manual disconnecting lever permits manual disconnection of the gearbox
• Regulation of the current torque prevents overloading and unnecessary run aborts
• Strong breakaway torque enables safe start-up even after an extended standstill
• Intelligent running behaviour. Recognises the difference between obstacles and dirt
• Spindle offset run: Excludes inconsistencies due to lash in the spindle.
• Condition monitoring of supply voltage, drag error (permits optimum adjustment of current position), power consumption and torque
• Partial safety function for STO (Safe Torque Off)

Dimensions in mm.

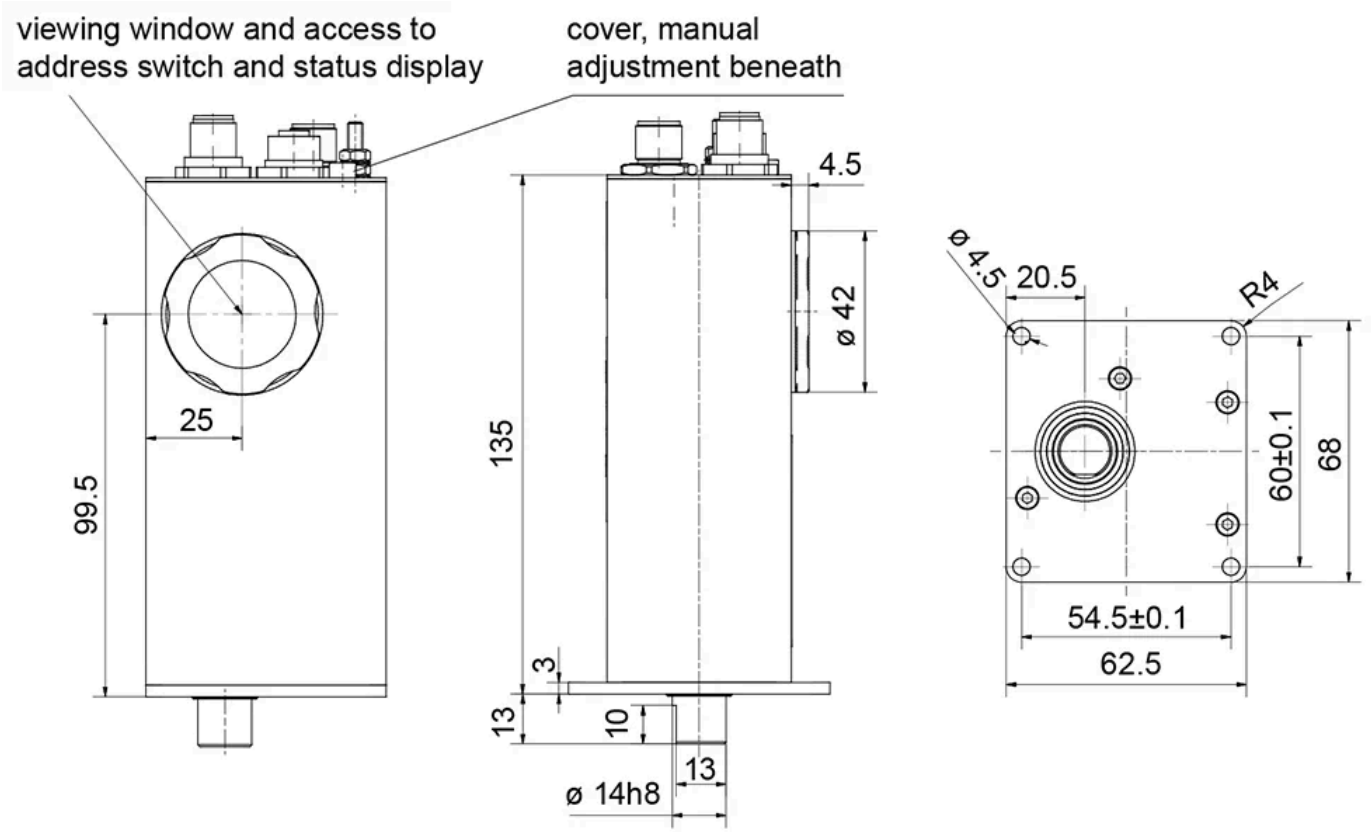
Contact us for CAD-files.

Type: Vertical
Nominal Voltage (V DC): 24 (± 10 %)
Nominal Current (A): 2.4
Output Shaft (mm): 14
Output Shaft Type: Solid
BUS Communication: Can Open (CA); Profi Bus (DP); Device Net (DN); Modbus (MB); IO-Link (IO); ProfiNet (PN); Sercos (SE); EtherCat (EC); Ethernet IP (EI); PowerLink (PL)
Electrical connection: "Standard; with jog keys; 1 connector Y-encoded or 1 connector Y-encoded with jog keys"
Protection Class: IP65
Motor: EC-motor
Supply Voltage: 24 V DC ± 10 % galvanically separated between control and motor and bus
Measurement System: Absolute, optical-magnetic
Accuracy: ± 0.9°
Intermittence: 20% (basis time 600 s)
Manual Adjustment: Standard
Brake: Optional (holding brake)
Material: Stainless steel housing. See pdf for details.

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General Data



Designation	Nominal Torque (Nm)	Nominal Speed (rpm)	Nominal Current (A)	Self-holding Torque (Nm)	Positioning Range (rot.)
PSS 311-14V	1	210	2.4	0.5	250
PSS 312-14V	2	115	2.4	1	250

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